

## TDA 4321 XS

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**FM-IF IC with counter output, analog STS, field strength  
indicator, noise detector and mute setting**

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**This specification replaces the previous editions**

DOK-Nr.	date	DOK-Nr.	date
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**TDA 4321 XS**

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**Functional Description, Application**

The FM-IF-Demodulator TDA 4321 XS has been developed especially for car radio applications. The on-chip multipath identification circuit activates an interference suppression circuit in case of multipath interferences.

The TDA 4321 XS includes an:

- 7stage limiter amplifier
- Coincidence demodulator
- Counter output with request input
- Field strength output
- Analog Multipath identification circuit
- Adjustable muting depth (with full muting  $\geq 80\text{dB}$ )
- STS function.

This device is ESD protected.

**TDA 4321 XS**

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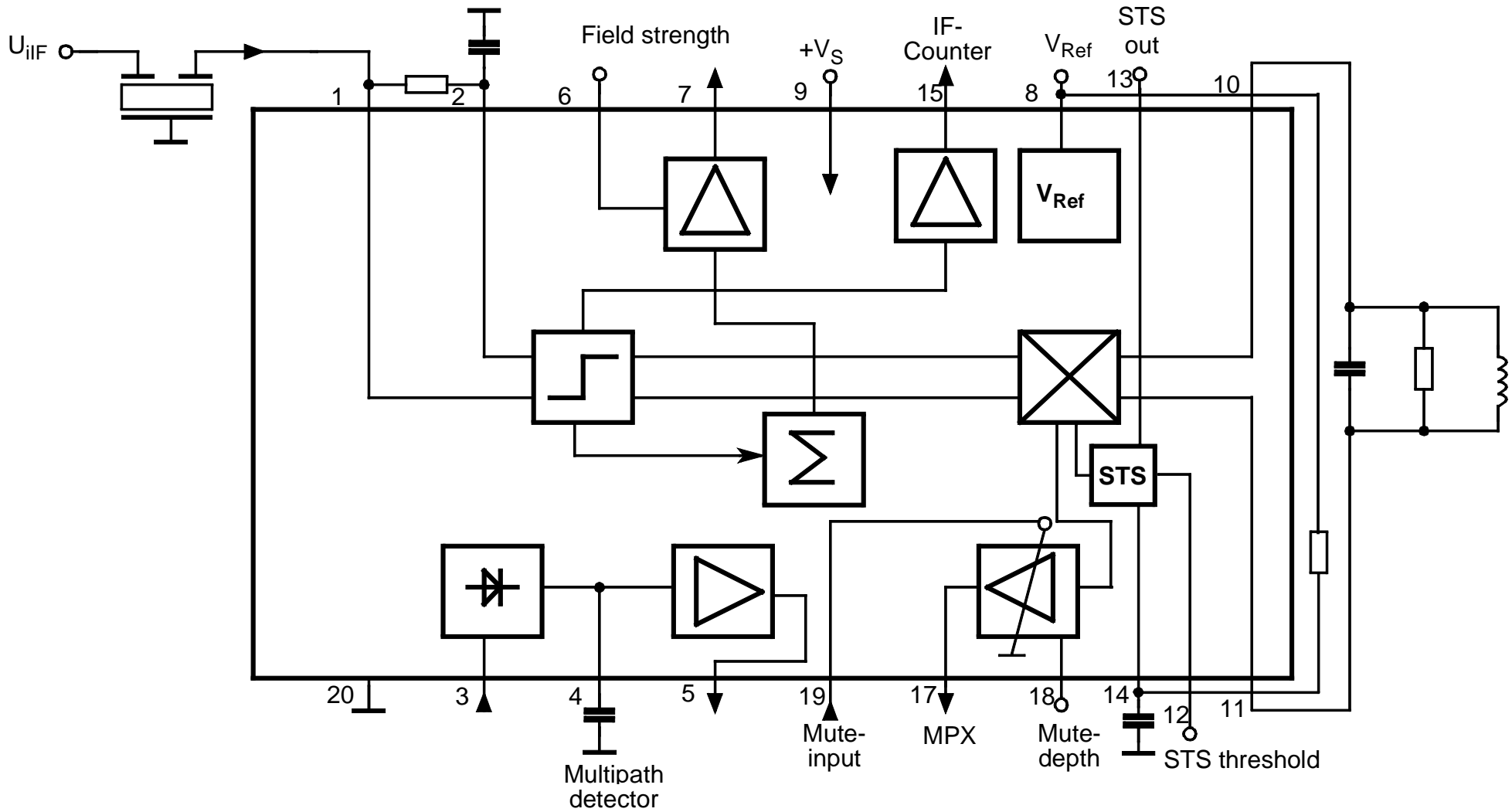
**Circuit Description**

The IC includes a 7 stage capacitive coupled-limiter amplifier with coincidence demodulator and AF output. The AF output signal can be continuously attenuated to decrease the noise.

In case of multipath interferences, the TDA 4321 XS includes an identification circuitry with analog output.

There is a field strength output (with min. 76 dB dynamic range, typ.  $\pm 1$  dB nonlinearity and typ.  $\pm 3$  dB temperature drift), an IF-Counter output and an adjustable muting (with full muting  $\geq 80$ dB). An STS output with adjustable threshold and stop window is available.

Block Diagram



**TDA 4321 XS**

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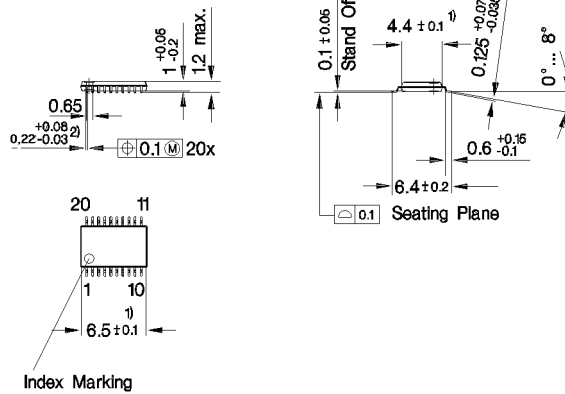
**Pin Assignment**

- 1 IF input
- 2 IF input bias
- 3 Multipath identification input
- 4 Rectifier time constant
- 5 Multipath identification output
- 6 Field strength adjust
- 7 Field strength output
- 8 Reference voltage output
- 9 Supply voltage
- 10 Demodulator circuit
- 11 Demodulator circuit
- 12 STS threshold
- 13 STS output
- 14 STS filter time constant and stop window width
- 15 IF-Counter output
- 16 NC
- 17 MPX output
- 18 Mute depth
- 19 Mute input
- 20 Ground

TDA 4321 XS

Package Outline

Plastic-Package  
TSSO-P 20-1



- 1) Does not include plastic or metal protrusion of 0.15 max. per side
- 2) Does not include dambar protrusion of 0.08 max. per side

## TDA 4321 XS

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**Absolute Maximum Ratings**

*The maximal ratings may not be exceeded under any circumstances, not even momentarily and individually, as permanent damage to the IC will result.*

#	Max. Ratings for ambient temperature $T_{amb}$ -40 °C to +85 °C	Symbol	Min	Max	Units	Remarks
1	Supply voltage	$V_S$	0	+13.5	V	
2	Junction temperature	$T_j$		+150	°C	
3	Storage temperature	$T_s$		+125	°C	
4	ESD voltage, HBM (1.5 k $\Omega$ ,100pF)	$V_{ESD}$	-4	+4	kV	
5	Thermal Resistance	$R_{thsa}$		115	K/W	

## TDA 4321 XS

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**Operational Range**

*Within the operational range the IC operates as described in the circuit description. The AC / DC characteristic limits are not guaranteed.*

#	Parameter	Symbol	Min	Max	Units	Remarks
1	Supply voltage	$V_S$	+7.5	+11	V	
2	Ambient temperature	$T_{amb}$	-40	+85	°C	



## TDA 4321 XS

## AC / DC Characteristics

AC / DC characteristics involve the spread of values guaranteed within the specified supply voltage and ambient temperature range. Typical characteristics are the median of the production.

#	Parameter	Symbol	Test Conditions	Test Circuit	Min	Typ	Max	Units
<b>Measuring condition:</b>								
$V_S = 10\text{ V}; f_{iIF} = 10.7\text{ MHz}; \Delta f = 75\text{ kHz}; f_{mod} = 1\text{ kHz}; V_{iIF} = 10\text{ mV}_{rms}; T_{amb} = +25^\circ\text{C}$								
1	Current consumption	$I_9$	$V_{19} = 4.8\text{ V}; V_{18} = 4\text{ V}$	1		33	41	mA
2	Stabilized voltage	$V_8$	$V_{19} = 4.8\text{ V}; V_{18} = 4\text{ V}$	1	4.5	4.8	5.1	V
3	Field strength output	$V_7$	$V_{19} = 4.8\text{ V}; V_{18} = 4\text{ V}$					
	-dynamic range			D1	74	80		dB
	-nonlinearity			D2		$\pm 1$		dB
	-temperature drift			D3			$\pm 3$	dB
	-Load capacitance						50	pF
	-Load resistance				1			k $\Omega$
		$V_7$	$V_{1rms} = 200\text{ mV}$	1	5	5.4	5.8	V
		$V_7$	$V_{1rms} = 1\text{ mV}$	1	2.3	2.7	3.1	V
		$V_7$	$V_{1rms} = 0\text{ mV}$	1	0		1.1	V
4	Input voltage for limiter threshold	$V_1$	$V_{17} = -3\text{ dB}$	1		20	30	$\mu\text{V}_{rms}$
5	AF-output voltage	$V_{17}$	$V_{19} = 4.8\text{ V}; V_{18} = 4\text{ V}$	1	460	550	640	$\text{mV}_{rms}$
6	AF-output voltage	$V_{17}$	$V_{19} = 4.8\text{ V}; V_{18} = 4\text{ V}$ $R_{10-11} = 2\text{ k}; \Delta f = 22,5\text{ kHz}$	Lab		80		$\text{mV}_{rms}$
7	Total harmonic distorton	THD <sub>17</sub>	$V_{19} = 4.8\text{ V}; V_{18} = 4\text{ V}$	1			0.8	%
8	AM-suppression	$a_{AM}$	$m = 80\%$	1	60			dB
			$m = 30\%$	1	70			dB
9	Signal-to-noise ratio	$a_{S/N}$	$V_{19} = 4.8\text{ V}; V_{18} = 4\text{ V}$	1	76	84		dB
10	Counter-output voltage	$V_{15}$	$C_L = 5\text{ pF}; R_{i15} = 1.5\text{ k}$	1	50	80		$\text{mV}_{rms}$

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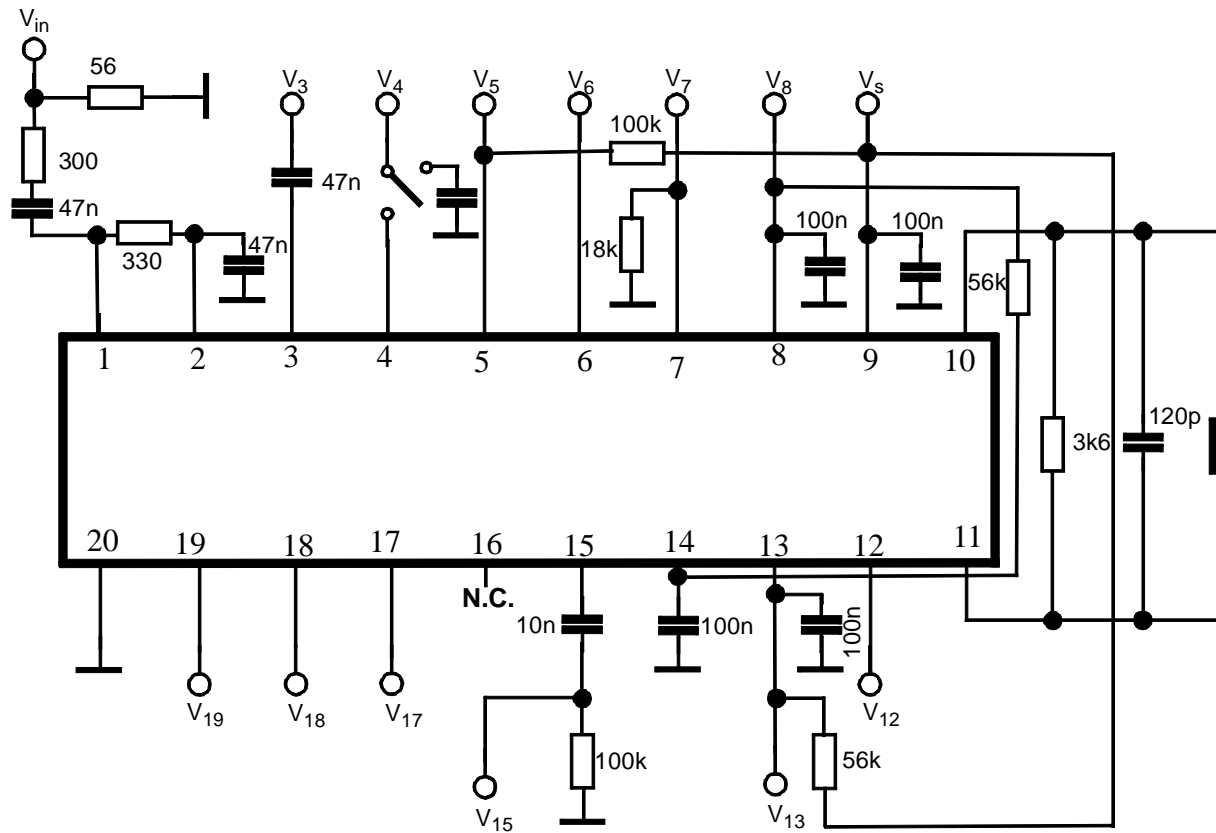
## AC / DC Characteristics

AC / DC characteristics involve the spread of values guaranteed within the specified supply voltage and ambient temperature range. Typical characteristics are the median of the production.

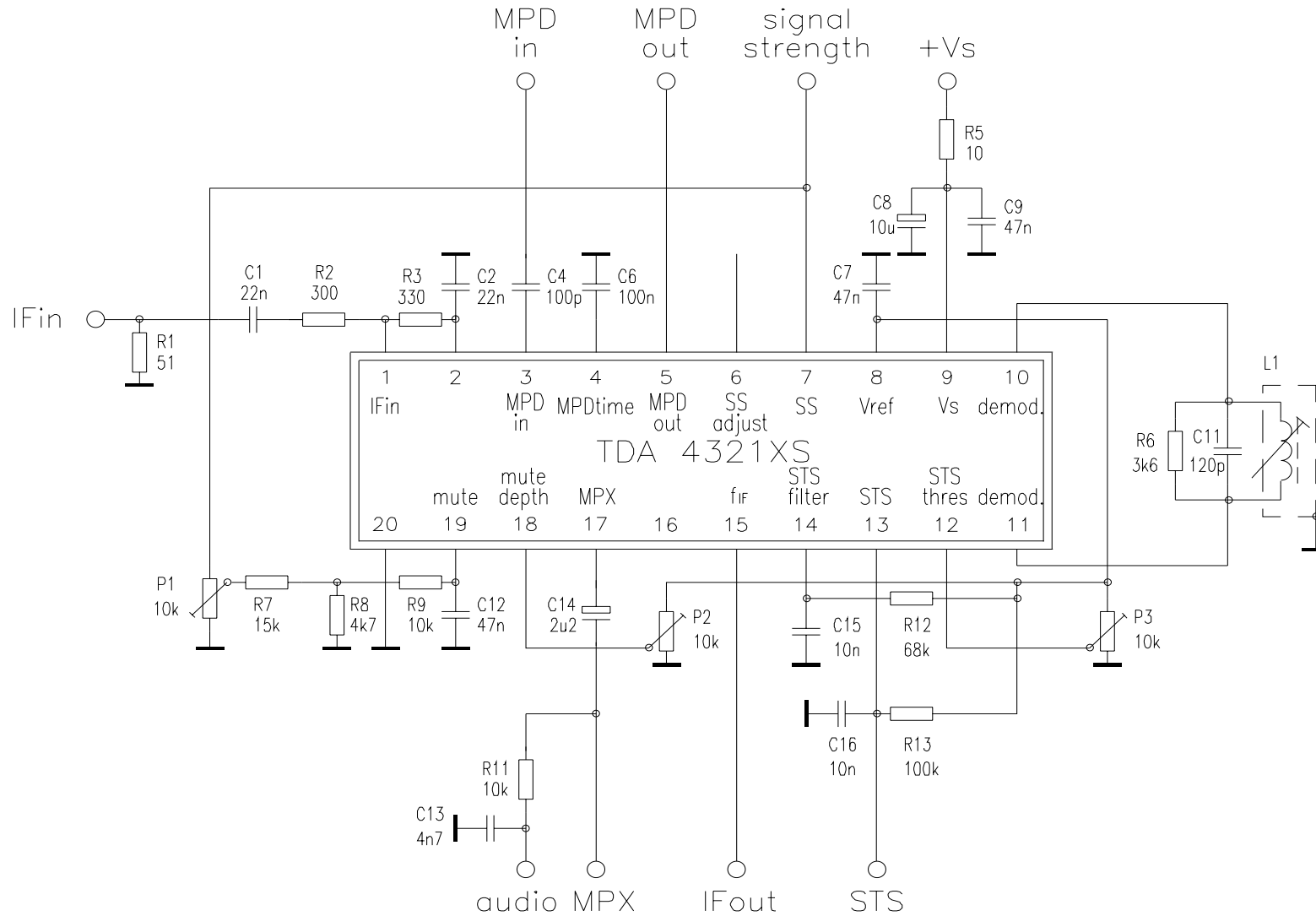
#	Parameter	Symbol	Test Conditions	Test Circuit	Min	Typ	Max	Units
<b>Measuring condition:</b> $V_S = 10\text{ V}$ ; $f_{\text{ilF}} = 10.7\text{ MHz}$ ; $\Delta f = 75\text{ kHz}$ ; $f_{\text{mod}} = 1\text{ kHz}$ ; $V_{\text{ilF}} = 10\text{ mV}_{\text{rms}}$ ; $T_{\text{amb}} = +25^\circ\text{C}$								
14	Attack current	$I_4^*$	$V_{3\text{AC}} = 1V_{\text{pp}}$ ; $V_m = 5.0\text{V}$	1	700	900	1100	$\mu\text{A}$
15	Recovery current	$I_4^*$	$V_{3\text{AC}} = 0\text{V}$ ; $V_m = 3.6\text{V}$	1	-6	-9	-12	$\mu\text{A}$
16	Start voltage	$V_{5\text{Def}}$	$V_{3\text{AC}} = 0\text{V}$	1	4.4	4.7		V
17	Detector characteristic	$V_5$	$V_3 = 100\text{mV}_{\text{pp}}$	1	$V_{5\text{Def}-3.5\text{V}}$	$V_{5\text{Def}-3\text{V}}$	$V_{5\text{Def}-2.5\text{V}}$	V
18	Detector characteristic	$V_5$	$V_3 = 350\text{mV}_{\text{pp}}$	1			500	mV
19	AF mute	$a_{\text{AF}}$	$V_{19} = 4.8\text{V}$ ; $V_{18} = 4.8\text{V}$	D4		0		dB
			$V_{19} = 0\text{V}$ ; $V_{18} = 4.8\text{V}$	D4	-2		2	dB
			$V_{19} = 0\text{V}$ ; $V_{18} = 2.4\text{V}$	D4	32	38	44	dB
			$V_{19} = 4.8\text{V}$ ; $V_{18} \leq 1.0\text{V}$	D4	80			dB
			$V_{19} = 0\text{V}$ ; $V_{18} \leq 1.0\text{V}$	D4	80			dB
20	Voltage for mute off	$V_{19}$		1	0.5			V
21	Voltage for mute on	$V_{19}$		1	0		0.1	V
22	Search tuning stop window	$f_{\text{STS13}}$	$R_{8-14} = 56\text{k}\Omega$	1			$\pm 25$	kHz
23	Search tuning stop offset	$f_{\text{STOffs}}$	$R_{8-14} = 56\text{k}\Omega$ ; THD = min	1			$\pm 10$	kHz
24	Search tuning stop threshold FM	$V_{\text{IST1}}$	$V_{12} = \text{open}$	1	50	100	200	$\mu\text{V}_{\text{rms}}$
			$V_{12} = 2.4\text{V}$	1	0.65	1.3	2.6	$\text{mV}_{\text{rms}}$

\*) Integrator currents are measured between the output pin (- Pole of the measurement equipment) and a voltage source  $V_m$  (+ Pole)

Test Circuit



Application Circuit

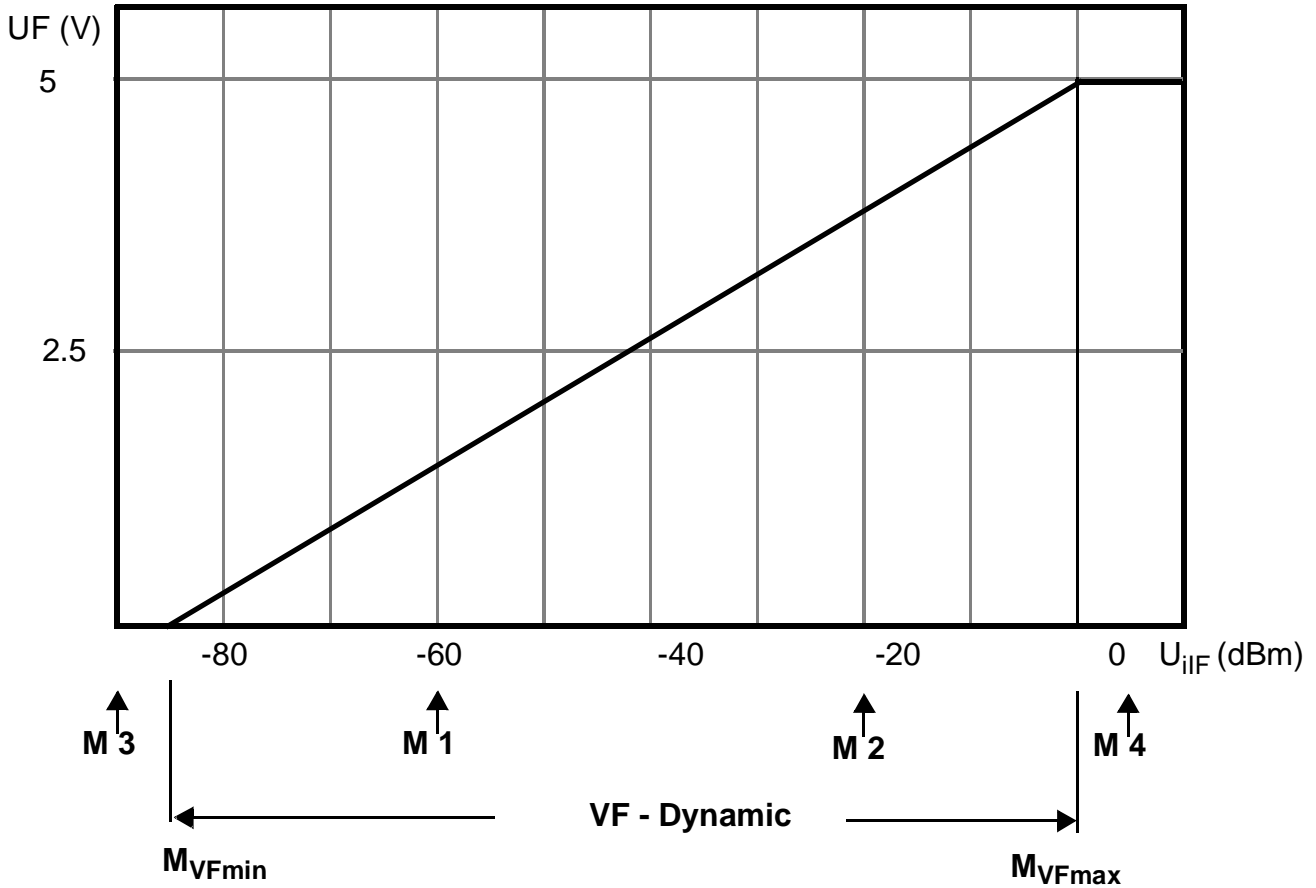


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Diagrams

$V_F$  Characteristic

D1



**$V_F$  - Dynamic** :The dynamic range of  $V_F$  voltage is determined by the test points M1 through M4 as follows:

- M1: test point (at  $V_{ilF} = -60$  dBm) supplies  $V_F$  (M1)
- M2: test point (at  $V_{ilF} = -20$  dBm) supplies  $V_F$  (M2)
- M3: test point (at  $V_{ilF} = -90$  dBm) supplies  $V_F$  (M3)
- M4: test point (at  $V_{ilF} = +5$  dBm) supplies  $V_F$  (M4)

Hence follows :

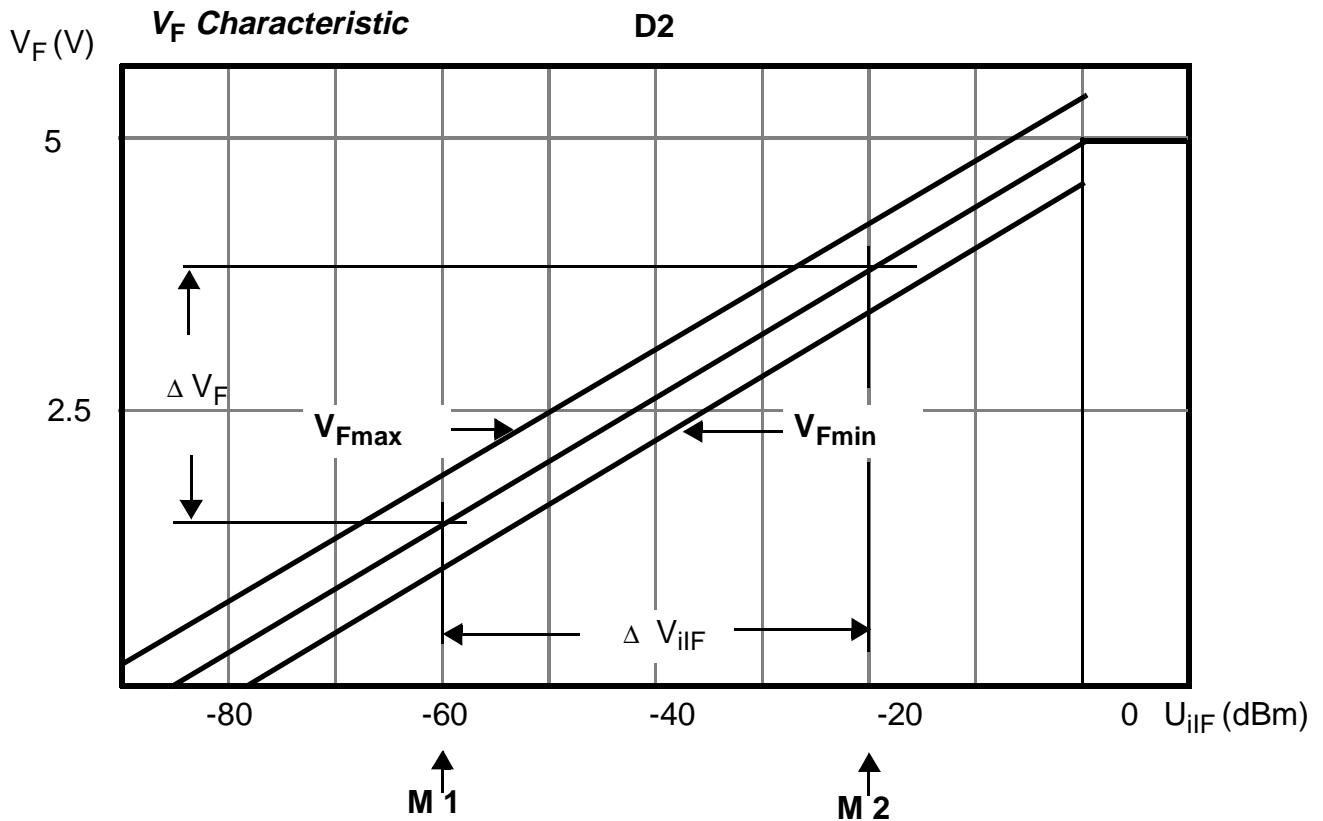
$$M_{VFmax} := -20 \text{ dBm} + \frac{U_F(M4) - U_F(M2)}{U_F(M2) - U_F(M1)} \times 40 \text{ dB}$$

$$M_{VFmin} := -60 \text{ dBm} - \frac{U_F(M1) - U_F(M3)}{U_F(M2) - U_F(M1)} \times 40 \text{ dB}$$

$$VF - Dynamic = M_{VFmax} - M_{VFmin}$$

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Diagrams



Test points to determine VF linearity

VF - Linearity: is determined at 25 °C

$$\text{Slope } : m = \frac{V_F (M2) - V_F (M1)}{40 \text{ dB}}$$

The tolerance range of the VF - linearity is determined by two parallel lines:

$$V_{Fmax} = V_F (M1) + m (M + 60 \text{ dB} + 1 \text{ dB})$$

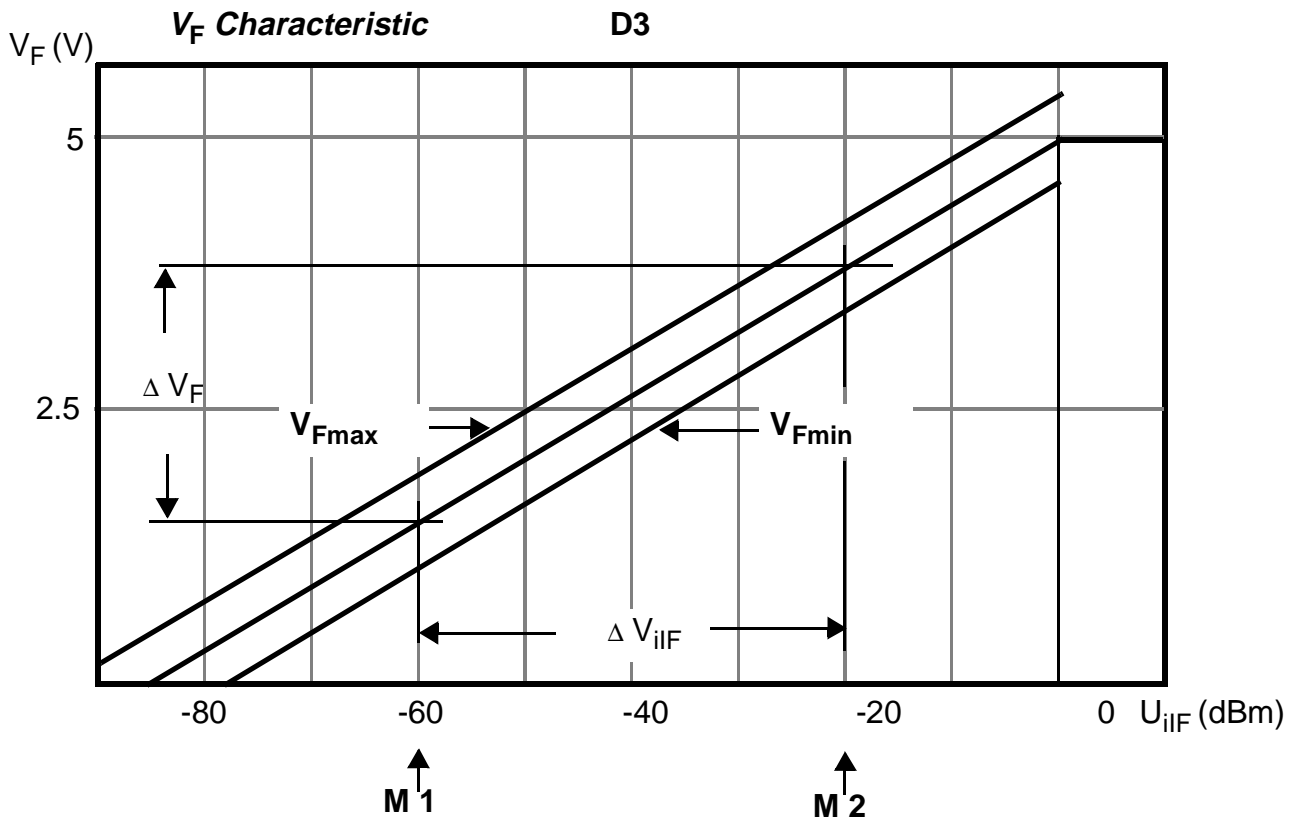
$$V_{Fmin} = V_F (M1) + m (M + 60 \text{ dB} - 1 \text{ dB})$$

The  $V_F$  values within the  $V_F$  dynamic range ( $M_{VFmin} \leq M \leq M_{VFmax}$ ) must be inside the predetermined tolerance range:

$$V_{Fmin} \leq V_F ( M ) \leq V_{Fmax}$$

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Diagrams



Test points to determine  $V_F$  temperature drift

$V_F$  -Temperatur - Drift : It is determined within -40 bis +85 °C

$$\text{Slope } : m = \frac{U_F (M2) - U_F (M1)}{40 \text{ dB}} \quad (\text{at } 25 \text{ }^\circ\text{C})$$

The tolerance range of the  $V_F$  temperature drift is determined by two parallel lines:

$$V_{Fmax} = V_F (M1) + m (M + 60 \text{ dB} + 3\text{dB})$$

$$V_{Fmin} = V_F (M1) + m (M + 60 \text{ dB} - 3\text{dB})$$

The  $V_F$  values for temperatures between -40 to +85 °C within the  $V_F$  dynamic range ( $M_{V_{Fmin}} \leq V_F \leq M_{V_{Fmax}}$ ) must be inside the predetermined tolerance field:

$$V_{Fmin} \leq V_F ( M ) \leq V_{Fmax}$$

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Diagrams

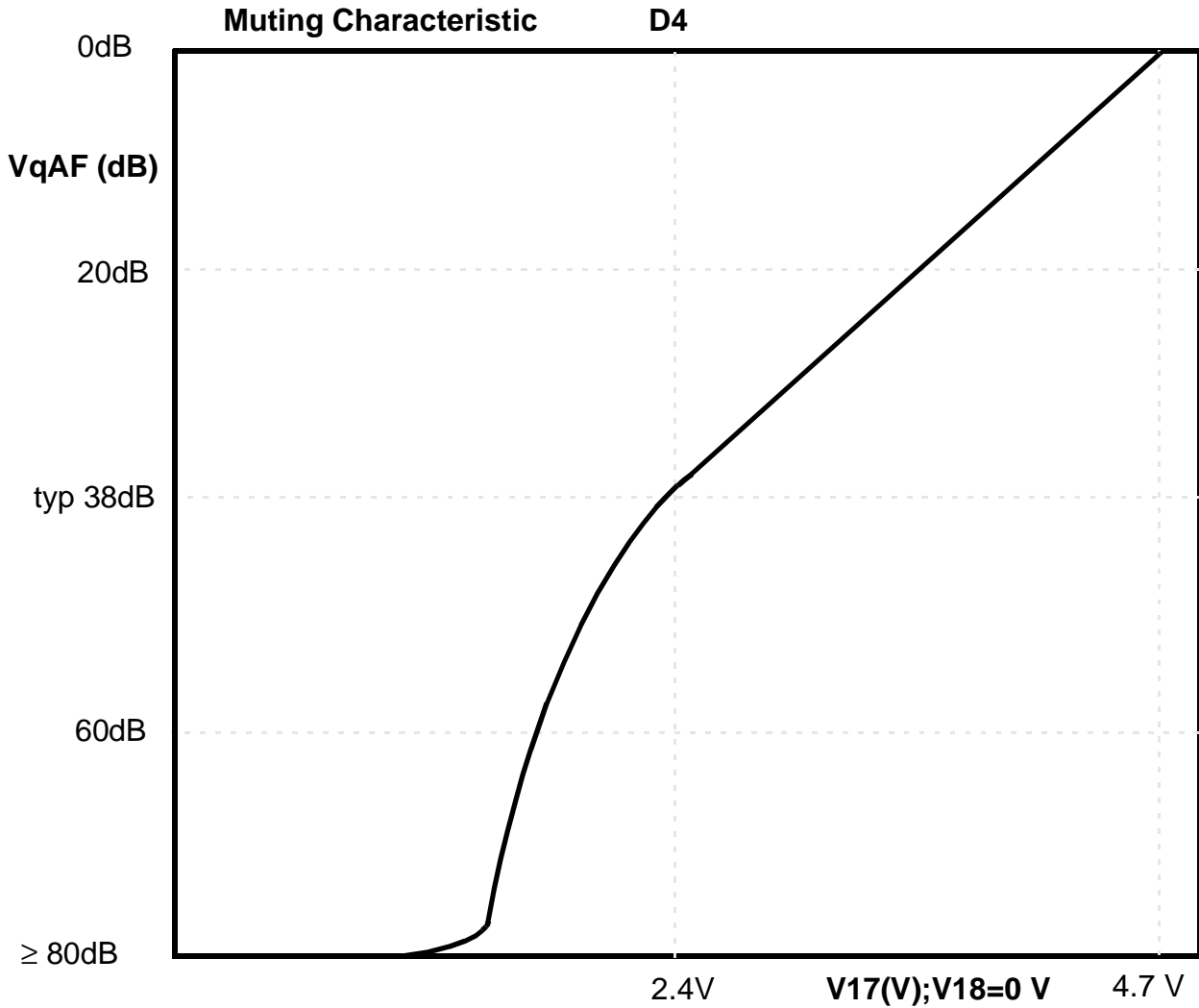


Diagram of Mute Characteristic