



## **OPA644**

# Low Distortion Current Feedback OPERATIONAL AMPLIFIER

## **FEATURES**

- SLEW RATE: 2500V/µs
- VERY LOW DIFFERENTIAL GAIN/PHASE ERROR: 0.008%/0.009°
- LOW DISTORTION AT 5MHz: -85dBc
- HIGH BANDWIDTH: 500MHz
- CLEAN PULSE RESPONSE
- HIGH OPEN LOOP TRANSIMPEDANCE:
   2.0MΩ
- HIGH LINEARITY
- FAST 12-BIT SETTLING: 21ns to 0.01%
- UNITY-GAIN STABLE

### **APPLICATIONS**

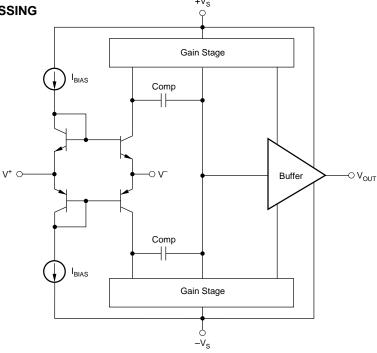
HIGH-SPEED SIGNAL PROCESSING

HIGH-RESOLUTION VIDEO

- PULSE AMPLIFICATION
- COMMUNICATIONS
- ADC/DAC GAIN AMPLIFIER
- RF AMPLIFICATION
- MEDICAL IMAGING
- AUDIO AMPLIFICATION

### DESCRIPTION

The OPA644 is a wideband precision current feedback operational amplifier featuring exceptionally high open loop transimpedance and high slew rate. The current feedback architecture allows for excellent large signal bandwidth, even at high gains. The high transimpedance allows this op amp to be used in applications requiring 16 bits or more of accuracy. This extra transimpedance at high bandwidths gives very low distortion and low differential gain and phase errors. The high slew rate and well-behaved pulse response allow for superior large signal amplification in a variety of RF, video and other signal processing applications. Fabricated on an advanced complementary bipolar process, the OPA644 offers exceptional performance in monolithic form.



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Tel: (520) 746-1111 • Twx: 910-952-1111 • Cable: BBRCORP • Telex: 066-6491 • FAX: (520) 889-1510 • Immediate Product Info: (800) 548-6132

# **SPECIFICATIONS**

### **ELECTRICAL**

 $T_{A} = +25^{\circ}C,\ V_{S} = \pm 5V,\ R_{L} = 100\Omega,\ C_{L} = 2pF,\ R_{FB} = 402\Omega \ and\ all\ four\ power\ supply\ pins\ are\ used\ unless\ otherwise\ noted.$ 

		OPA644H, P, U		OPA644HSQ, PB, UB				
PARAMETER	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
OFFSET VOLTAGE								
Input Offset Voltage	G = +10		±2.5	±6		±2	±3	mV
Average Drift			20			10		μV/°C
HSQ Grade Average Drift						20	35	μV/°C
Power Supply Rejection	$V_{S} = \pm 4.5 \text{ to } \pm 5.5 \text{V}$	40	65		60	75		dB
INPUT BIAS CURRENT(1)								
Non-Inverting			±20	±40		±15	±20	μΑ
Over Specified Temperature			±24	±90		±20	±50	μΑ
HSQ Grade Over Temperature						35	60	μΑ
Inverting			±2	±25		*	±10	μΑ
Over Specified Temperature			±4	±35		±3	±25	μΑ
HSQ Grade Over Temperature						±5	±25	μΑ
NOISE								
Input Voltage Noise Density	G = +10							
f = 100Hz			10.3			*		nV/√ <del>Hz</del>
f = 1kHz			2.9			*		nV/√ <del>Hz</del>
f = 10kHz			1.9			*		nV/√ <del>Hz</del>
f = 1MHz			1.9			*		nV/√Hz
$f_B = 100Hz$ to 200MHz			33.6			*		μVrms
Inverting Input Bias Current								' '
Noise Density: f = 10MHz			15			*		pA/√Hz
Non-Inverting Input Current								
Noise Density: f = 10MHz			15			*		pA/√Hz
INPUT VOLTAGE RANGE								<u> </u>
Common-Mode Input Range		±2.0	±2.25		*	*		V
Over Specified Temperature		±1.8	±2.1		*	*		l v
Common-Mode Rejection	$V_{CM} = \pm 2V$	35	55		45	65		dB
INPUT IMPEDANCE	- CM	+						<del></del>
Non-Inverting			500    1.0			*		kΩ    pF
Inverting			20			46		Ω
Open-Loop Transimpedance	$V_O = \pm 2V, R_L = 1k\Omega$	1.4	2.0		*	*		MΩ
FREQUENCY RESPONSE, R <sub>FB</sub> = 402	-	···	2.0					11122
Closed-Loop Bandwidth	G = +1V/V		500			*		MHz
Closed-Loop Bandwidth	G = +1V/V G = +2V/V		300			*		MHz
						*		
	G = +5V/V		180			*		MHz MHz
	G = +10V/V		125 80			*		MHz
Slew Rate <sup>(1)</sup>	G = +20V/V		1			*		1
	G = +2, 2V Step		2500 21			*		V/μs
Settling Time: 0.01%	G = +2, 2V Step		16.5			*		ns
0.1% 1%	G = +2, 2V Step G = +2, 2V Step		1			*		ns
	G = +2, 2V Step		5.5			*		ns
Overload Recovery Time <sup>(2)</sup> Spurious Free Dynamic Range	C 1 f 5 0MH=		60 84			86		ns dBc
Spurious Free Dynamic Range	G = -1, $f = 5.0MHz$		04			00		ubc
	$V_0 = 2Vp-p$ G = -1, f = 20MHz							dBc
Differential Gain Error at 3.58MHz	G = -1, 1 = 200012 $G = +2V/V, V_0 = 0V \text{ to } 1.4V$		0.008			*		%
Differential Gain Entit at 3.56MHz	$G = +20/V, V_0 = 00 \text{ to } 1.4V$ $R_L = 150\Omega$		0.006					70
Differential Phase Error at 3.58MHz	$G = +2V/V, V_O = 0V \text{ to } 1.4V$		0.009			*		Degrees
Dinordiniar i nade Ellor at 0.00MHZ	$R_1 = 150\Omega$		0.003					Dogrees
Gain Flatness to 1dB	G = +1		250			*		MHz
OUTPUT		1						.,,,,,
Current Output		±40	±60		±50	±66		mA
•			1			1		
Over Specified Temperature	No Load	±30	±45		±40	±50		mA
Voltage Output	INO LOAG	12.0	12.5		*	*		.,
Over Specified Temperature	B 4000	±3.0	±3.5					V
Voltage Output	$R_L = 100\Omega$	10.75	10.05					.,
Over Specified Temperature		±2.75	±3.25			•		V
Short Circuit Current	40415 0 :00/0/		75				] .	mA
Output Resistance	1MHz, G = +2V/V	1	0.2					Ω
POWER SUPPLY	_							
Specified Operating Voltage	$T_{MIN}$ to $T_{MAX}$		±5			*		V
Operating Voltage Range	$T_{MIN}$ to $T_{MAX}$	±4.5		±5.5	*		*	٧.
Quiescent Current	T <sub>MIN</sub> to T <sub>MAX</sub>		±18	±26	l	*	*	mA



### SPECIFICATIONS (CONT)

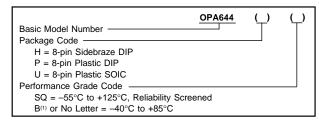
#### **ELECTRICAL**

 $T_A$  = +25°C,  $V_S$  = ±5V,  $R_L$  = 100 $\Omega$ ,  $C_L$  = 2pF,  $R_{FB}$  = 402 $\Omega$  and all four power supply pins are used unless otherwise noted.  $R_{FB}$  = 25 $\Omega$  for a gain of +1.

		OPA644H, P, U		OPA644HSQ, PB UB				
PARAMETER	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
TEMPERATURE RANGE								
Specification: H, P, U		-40		+85	*		*	°C
HSQ					<b>-</b> 55		+125	°C
Thermal Resistance, $\theta_{JA}$								
Р			120			*		°C/W
U			170			*		°C/W
Н			120			*		°C/W

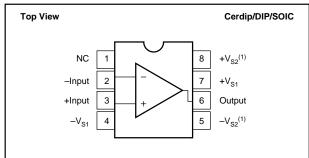
NOTES: (1) Slew rate is rate of change from 10% to 90% of the output voltage step. (2) Time for the output to resume linear operation after saturation.

#### **ORDERING INFORMATION**



NOTE: (1) The "B" Grade of the SOIC package will be marked with a "B" by pin 8. Refer to the mechanical section for the location.

#### PIN CONFIGURATION (All Packages)



NOTE: (1) Making use of all four power supply pins is highly recommended, although not required. Using these four pins, instead of just pins 4 and 7, will lower the effective pin impedance and substantially lower distortion.

#### **ABSOLUTE MAXIMUM RATINGS**

Supply	±5.5VDC
Internal Power Dissipation <sup>(1)</sup>	
Differential Input Voltage	Total V <sub>CC</sub>
Input Voltage Range	See Applications Information
Storage Temperature Range: H, HSC	065°C to +150°C
P, PB,	U, UB40°C to +125°C
Lead Temperature (soldering, 10s)	+300°C
(soldering, SOIC 3	s)+260°C
Junction Temperature (T <sub>J</sub> )	+175°C
NOTE: (1) Packages must be derated $T_J$ must be observed.	based on specified $\theta_{\mathrm{JA}}.$ Maximum

#### **PACKAGE INFORMATION**

MODEL	PACKAGE	PACKAGE DRAWING NUMBER <sup>(1)</sup>
OPA644H, HSQ	8-Pin Cerdip	157
OPA644P, PB OPA644U, UB	8-Pin DIP 8-Pin SOIC	006 182

NOTE: (1) For detailed drawing and dimension table, please see end of data sheet, or Appendix D of Burr-Brown IC Data Book.



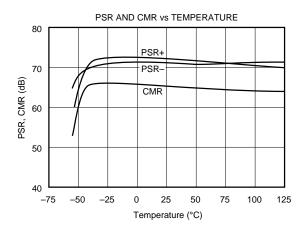
Electrostatic discharge can cause damage ranging from performance degradation to complete device failure. Burr-Brown Corporation recommends that all integrated circuits be handled and stored using appropriate ESD protection methods.

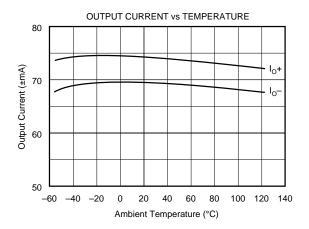
ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet published specifications.

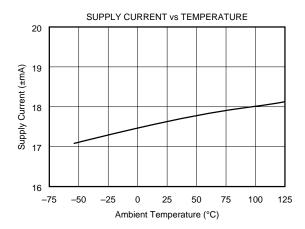
The information provided herein is believed to be reliable; however, BURR-BROWN assumes no responsibility for inaccuracies or omissions. BURR-BROWN assumes no responsibility for the use of this information, and all use of such information shall be entirely at the user's own risk. Prices and specifications are subject to change without notice. No patent rights or licenses to any of the circuits described herein are implied or granted to any third party. BURR-BROWN does not authorize or warrant any BURR-BROWN product for use in life support devices and/or systems.

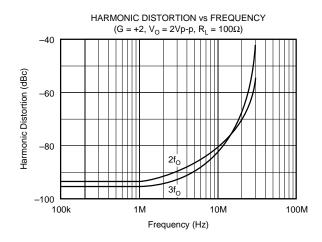
## **TYPICAL PERFORMANCE CURVES**

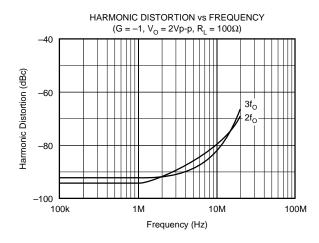
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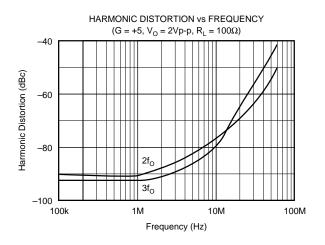








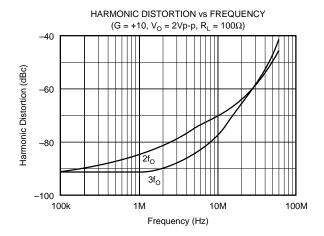


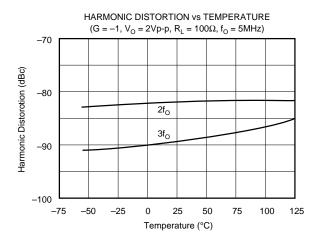


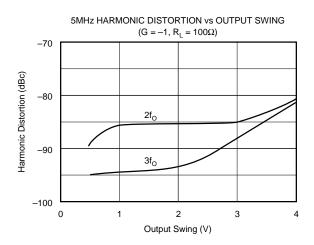


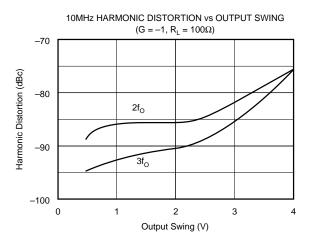
## TYPICAL PERFORMANCE CURVES (CONT.)

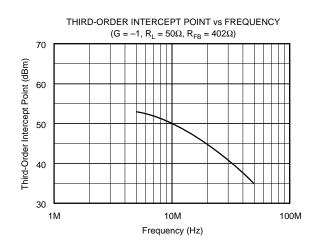
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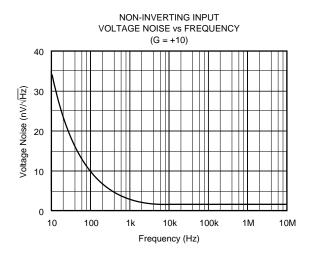








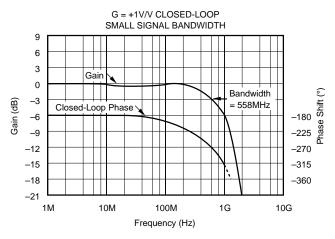


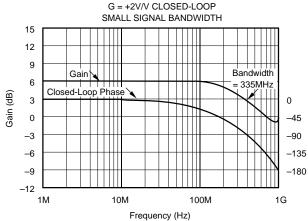


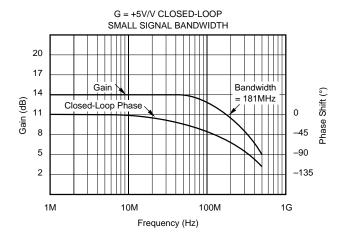
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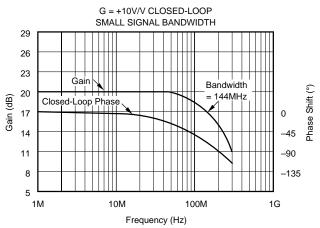
### TYPICAL PERFORMANCE CURVES (CONT)

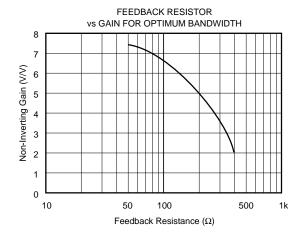
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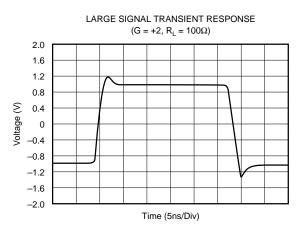








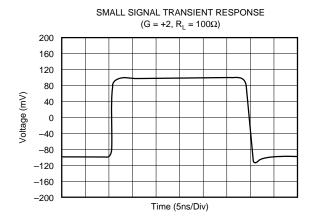


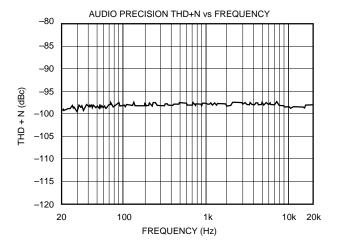


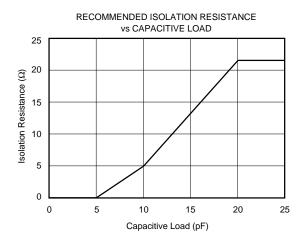


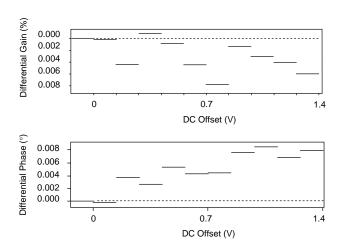
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## **APPLICATIONS INFORMATION**

#### THEORY OF OPERATION

This current feedback architecture offers the following important advantages over voltage feedback architectures: (1) the high slew rate allows the large signal performance to approach the small signal performance, and: (2) there is very little bandwidth degradation at higher gain settings.

The current feedback architecture of the OPA644 provides the traditional strength of excellent large signal response with the unusual addition of very high open-loop transimpedance. This high open-loop transimpedance allows the OPA644 to be used in applications requiring 16 bits or more of accuracy and dynamic linearity.

#### DC GAIN TRANSFER CHARACTERISTICS

The circuit in Figure 1 shows the equivalent circuit for calculating the DC gain. When operating the device in the inverting mode, the input signal error current ( $I_E$ ) is amplified by the open-loop transimpedance gain ( $T_O$ ). The output signal generated is equal to  $T_O$  x  $T_E$ . Negative feedback is applied through  $T_E$  such that the device operates at a gain equal to  $T_E$ 0 for  $T_E$ 1.

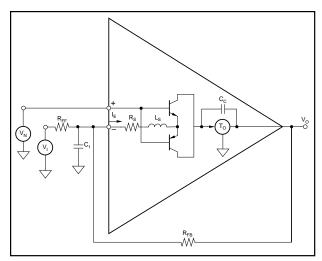


FIGURE 1. Equivalent Circuit.

For non-inverting operation, the input signal is applied to the non-inverting (high impedance buffer) input. The output (buffer) error current ( $I_E$ ) is generated at the low impedance inverting input. The signal generated at the output is fed back to the inverting input such that the overall gain is (1 +  $R_{FF}/R_I$ ).

Where a voltage-feedback amplifier has two symmetrical high impedance inputs, a current feedback amplifier has a low inverting (buffer output) impedance and a high noninverting (buffer input) impedance.

The closed-loop gain for the OPA644 can be calculated using the following equations:

Inverting Gain = 
$$(-R_{FB}/R_{FF})/(1+1/Loop Gain)$$
 (1)

Non-inverting Gain = 
$$(1 + R_{FB}/R_{FF})/(1 + 1/Loop Gain)$$
 (2)  
where: Loop Gain =  $T(o)/(R_{FB})$  x  $(1/(1+T(o)/(R_{FB}/R_{FF}))$ 

At higher gains the small value inverting input impedance  $(R_{\text{INV}})$  causes an apparent loss in bandwidth. This can be seen from the equation:

Factual = 
$$F_{IDEAL}/(1 + (R_{INV}/R_{FB}) (1 + R_{FB}/R_{FF}))$$
 (3)

This loss in bandwidth at high gains can be corrected without affecting stability by lowering the value of the feedback resistor from the specified value of  $402\Omega$ .

#### OFFSET VOLTAGE AND NOISE

The output offset is the algebraic sum of the input voltage and current sources that influence DC operation. The output offset is calculated by the following equation:

Output Offset Voltage = 
$$\pm Ib_N$$
 x  $R_N$  (1 +  $R_{FB}/R_G$ )  $\pm V_{IO}$  (4) (1 +  $R_{FB}/R_G$ )  $\pm Ib_I$  x  $R_{FB}$ 

If all terms are divided by the gain  $(1 + R_F/R_G)$  it can be observed that input referred offsets improve as gain increases.

The effective noise at the output of the amplifier can be determined by taking the root sum of the squares of equation 4 and applying the spectral noise values found in the Typical Performance Curve graph section. This applies to noise from the op amp only. Note that both the noise figure and equivalent input offset voltages improve as the closed-loop gain increases (by keeping  $R_{\rm F}$  fixed and reducing  $R_{\rm I}$  with  $R_{\rm N}=0\Omega$ ).

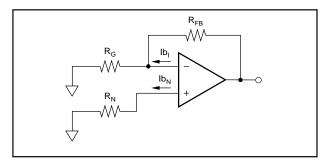


FIGURE 2. Output Offset Voltage Equivalent Circuit.

#### **INCREASING BANDWIDTH AT HIGH GAINS**

The closed-loop bandwidth can be extended at high gains by reducing the value of the feedback resistor  $R_{FB}$  (refer to Figure 1). This bandwidth reduction is caused by the feedback current being split between  $R_{S}$  and  $R_{FF}.$  As the gain increases (for a fixed  $R_{FB}$ ), more feedback current is shunted through  $R_{FF}$ , which reduces closed-loop bandwidth. To maintain specified bandwidth, the following equations can be used to approximate  $R_{F}$  and  $R_{I}$  for any gain from  $\pm 1$  to  $\pm 15$ :

 $R_{FB} = 424 \pm 8G$  (+ for inverting and – for non-inverting)

 $R_{FF} = (424 - 8G)/(G - 1)$  (non-inverting)

 $R_1 = (424 + 8G)/G$  (inverting)

G = Closed-loop gain

#### WIRING PRECAUTIONS

Maximizing the OPA644's capability requires some wiring precautions and high-frequency layout techniques. Oscillation, ringing, poor bandwidth and settling, gain peaking, and instability are typical problems plaguing all high-speed amplifiers when they are improperly used. In general, all printed circuit board conductors should be wide to provide low resistance, low impedance signal paths. They should also be as short as possible. The entire physical circuit should be as small as practical. Stray capacitances should be minimized, especially at high impedance nodes, such as the amplifier's input terminals. Stray signal coupling from the output or power supplies to the inputs should be minimized. All circuit element leads should be no longer than 1/4 inch (6mm) to minimize lead inductance, and low values of resistance should be used. This will minimize time constants formed with the circuit capacitances and will eliminate stray, parasitic circuits.

Grounding is the most important application consideration for the OPA644, as it is with all high-frequency circuits. Oscillations at high frequencies can easily occur if good grounding techniques are not used. A heavy ground plane (2 oz. copper recommended) should connect all unused areas on the component side. Good ground planes can reduce stray signal pickup, provide a low resistance, low inductance common return path for signal and power, and can conduct heat from active circuit package pins into ambient air by convection.

Supply bypassing is extremely critical and must *always* be used, especially when driving high current loads. Both power supply leads should be bypassed to ground as close as possible to the amplifier pins. Tantalum capacitors (2.2µF) with very short leads are recommended. A parallel 0.01µF ceramic must also be added. Surface-mount bypass capacitors will produce excellent results due to their low lead inductance. Additionally, suppression filters can be used to isolate noisy supply lines. Properly bypassed and modulation-free power supply lines allow full amplifier output and optimum settling time performance.

#### Points to Remember

1) Making use of all four power supply pins will lower the effective power supply inductance seen by the input and output stages. This will improve the AC performance including lower distortion. The lowest distortion is achieved when running separated traces to  $V_{S1}$  and  $V_{S2}$ . Power supply bypassing with  $0.01\mu F$  and  $2.2\mu F$  surface-mount capacitors is recommended. It is essential to keep the  $0.01\mu F$  capacitor very close to the power supply pins. Refer to the demonstration board figure in the DEM-OPA64X datasheet for the recommended layout and component placements.

- (2) Whenever possible, use surface mount. Don't use pointto-point wiring as the increase in wiring inductance will be detrimental to AC performance. However, if it must be used, very short, direct signal paths are required. The input signal ground return, the load ground return, and the power supply common should all be connected to the same physical point to eliminate ground loops, which can cause unwanted feedback
- 3) Surface mount on the backside of the PC Board. Good component selection is essential. Capacitors used in critical locations should be a low inductance type with a high quality dielectric material. Likewise, diodes used in critical locations should be Schottky barrier types, such as HP5082-2835 for fast recovery and minimum charge storage. Ordinary diodes will not be suitable in RF circuits.
- 4) Whenever possible, solder the OPA644 directly into the PC board without using a socket. Sockets add parasitic capacitance and inductance, which can seriously degrade AC performance or produce oscillations.
- 5) Use a small feedback resistor (usually  $25\Omega$ ) in unity-gain voltage follower applications for the best performance. For gain configurations, resistors used in feedback networks should have values of a few hundred ohms for best performance. Shunt capacitance problems limit the acceptable resistance range to about  $1k\Omega$  on the high end and to a value that is within the amplifier's output drive limits on the low end. Metal film and carbon resistors will be satisfactory, but wirewound resistors (even "non-inductive" types) are absolutely unacceptable in high-frequency circuits. Feedback resistors should be placed directly between the output and the inverting input on the backside of the PC board. This placement allows for the shortest feedback path and the highest bandwidth. A longer feedback path than this will decrease the realized bandwidth substantially. Refer to the demonstration board layout at the end of the datasheet.
- 6) Surface-mount components (chip resistors, capacitors, etc.) have low lead inductance and are therefore strongly recommended. Circuits using all surface-mount components with the OPA644U (SOIC package) will offer the best AC performance. The parasitic package impedance for the SOIC is lower than the both the Cerdip and 8-lead Plastic DIP.
- 7) Avoid overloading the output. Remember that output current must be provided by the amplifier to drive its own feedback network as well as to drive its load. Lowest distortion is achieved with high impedance loads.
- 8) Don't forget that these amplifiers use  $\pm 5V$  supplies. Although they will operate perfectly well with +5V and -5.2V, use of  $\pm 15V$  supplies will destroy the part.
- 9) Standard commercial test equipment has not been designed to test devices in the OPA644's speed range. Benchtop op amp testers and ATE systems will require a special test head to successfully test these amplifiers.
- 10) Terminate transmission line loads. Unterminated lines, such as coaxial cable, can appear to the amplifier to be a capacitive or inductive load. By terminating a transmission line with its characteristic impedance, the amplifier's load then appears purely resistive.

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11) Plug-in prototype boards and wire-wrap boards will not be satisfactory. A clean layout using RF techniques is essential; there are no shortcuts.

#### INPUT PROTECTION

Static damage has been well recognized for MOSFET devices, but any semiconductor device deserves protection from this potentially damaging source. The OPA644 incorporates on-chip ESD protection diodes as shown in Figure 3. This eliminates the need for the user to add external protection diodes, which can add capacitance and degrade AC performance.

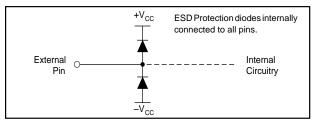


FIGURE 3. Internal ESD Protection.

All pins on the OPA644 are internally protected from ESD by means of a pair of back-to-back reverse-biased diodes to either power supply as shown. These diodes will begin to conduct when the input voltage exceeds either power supply by about 0.7V. This situation can occur with loss of the amplifier's power supplies while a signal source is still present. The diodes can typically withstand a continuous current of 30mA without destruction. To insure long term reliability, however, diode current should be externally limited to 10mA or so whenever possible.

The OPA644 utilizes a fine geometry high speed process that withstands 500V using the Human Body Model and 100V using the machine model. However, static damage can cause subtle changes in amplifier input characteristics without necessarily destroying the device. In precision operational amplifiers, this may cause a noticeable degradation of offset voltage and drift. Therefore, static protection is strongly recommended when handling the OPA644.

#### **OUTPUT DRIVE CAPABILITY**

The OPA644 has been optimized to drive  $75\Omega$  and  $100\Omega$  resistive loads. The device can drive 2Vp-p into a  $75\Omega$  load. This high-output drive capability makes the OPA644 an ideal choice for a wide range of RF, IF, and video applications. In many cases, additional buffer amplifiers are unneeded.

Many demanding high-speed applications such as ADC/DAC buffers require op amps with low wideband output impedance. For example, low output impedance is essential when driving the signal-dependent capacitances at the inputs of flash A/D converters. As shown in Figure 4, the OPA644 maintains very low closed-loop output impedance over frequency. Closed-loop output impedance increases with frequency since loop gain is decreasing with frequency.

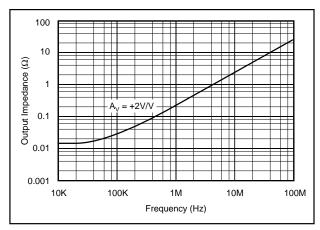


FIGURE 4. Closed-Loop Output Impedance vs Frequency.

### THERMAL CONSIDERATIONS

The OPA644 does not require a heat sink for operation in most environments. At extreme temperatures and under full load conditions a heat sink may be necessary.

The internal power dissipation is given by the equation  $P_D = P_{DQ} + P_{DL}$ , where  $P_{DQ}$  is the quiescent power dissipation and  $P_{DL}$  is the power dissipation in the output stage due to the load. (For  $\pm V_{CC} = \pm 5V$ ,  $P_{DQ} = 10V$  x 26mA = 260mW, max). For the case where the amplifier is driving a grounded load ( $R_L$ ) with a DC voltage ( $\pm V_{OUT}$ ) the maximum value of  $P_{DL}$  occurs at  $\pm V_{OUT} = \pm V_{CC}/2$ , and is equal to  $P_{DL}$ , max =  $(\pm V_{CC})^2/4R_L$ . Note that it is the voltage across the output transistor, and not the load, that determines the power dissipated in the output stage.

The short-circuit condition represents the maximum amount of internal power dissipation that can be generated. The variation of output current with temperature is shown in the Typical Performance Curves.

### **CAPACITIVE LOADS**

The OPA644's output stage has been optimized to drive low resistive loads. Capacitive loads, however, will decrease the amplifier's phase margin which may cause high frequency peaking or oscillations. Capacitive loads greater than 5pF should be buffered by connecting a small resistance, usually  $5\Omega$  to  $25\Omega$ , in series with the output as shown in Figure 5. This is particularly important when driving high capacitance loads such as flash A/D converters.

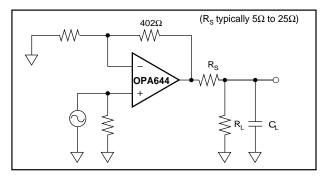


FIGURE 5. Driving Capacitive Loads.



In general, capacitive loads should be minimized for optimum high frequency performance. Coax lines can be driven if the cable is properly terminated. The capacitance of coax cable (29pF/foot for RG-58) will not load the amplifier when the coaxial cable or transmission line is terminated in its characteristic impedance.

#### **COMPENSATION**

The OPA644 is internally compensated and is stable in unity gain with a phase margin of approximately  $70^{\circ}$ . (Note that, from a stability standpoint, an inverting gain of -1V/V is equivalent to a noise gain of 2.) Gain and phase response for other gains are shown in the Typical Performance Curves. The high-frequency response of the OPA644 in a good

#### **DISTORTION**

layout is very flat with frequency.

The OPA644's harmonic distortion characteristics into a  $100\Omega$  load are shown vs frequency and power output in the Typical Performance Curves. Distortion can be further improved by increasing the load resistance as illustrated in Figure 6. Remember to include the contribution of the feedback resistance when calculating the effective load resistance seen by the amplifier.

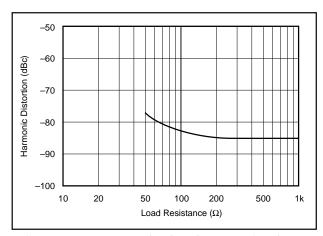


FIGURE 6. 5MHz Harmonic Distortion vs Load Resistance.

The third-order intercept is an important parameter for many RF amplifier applications. Figure 6 shows the OPA644's single tone third-order intercept vs frequency. This curve is particularly useful for determining the magnitude of the third harmonic as a function of frequency, load resistance, and gain. For example, assume that the application requires the OPA644 to operate in a gain of +2V/V and drive 2Vp-p into  $50\Omega$  at a frequency of 10MHz. Referring to Figure 6 we find that the intercept point is +50dBm. The magnitude of the third harmonic can now be easily calculated from the expression:

$$\label{eq:continuous} \begin{split} \text{Third Harmonic (dBc)} &= 2(OPI^3P - P_O) \\ \text{where OPI}^3P &= \text{third-order output intercept, dBm} \\ P_O &= \text{output level, dBm} \end{split}$$

For this case  $OPI^3P = 60dBm$ ,  $P_O = 10dBm$ , and the third harmonic = 2(50 - 10) = 80dB below the fundamental. The OPA644's low distortion makes the device an excellent choice for a variety of RF signal processing applications.

#### **DIFFERENTIAL GAIN AND PHASE**

Differential Gain (DG) and Differential Phase (DP) are among the more important specifications for video applications. DG is defined as the percent change in closed-loop gain over a specified change in output voltage level. DP is defined as the change in degrees of the closed-loop phase over the same output voltage change. Both DG and DP are specified at the NTSC sub-carrier frequency of 3.58MHz and the PAL subcarrier of 4.43MHz. All NTSC measurements were performed using a Tektronix model VM700A Video Measurement Set.

DG and DP of the OPA644 were measured with the amplifier in a gain of +2V/V with 75 $\Omega$  input impedance and the output back-terminated in 75 $\Omega$ . The input signal selected from the generator was a 0V to 1.4V modulated ramp with sync pulse. With these conditions the test circuit shown in Figure 7 delivered a 100IRE modulated ramp to the 75 $\Omega$  input of the video analyzer. The signal averaging feature of the analyzer was used to establish a reference against which the performance of the amplifier was measured. Signal averaging was also used to measure the DG and DP of the test signal in order to eliminate the generator's contribution to measured amplifier performance. Typical performance of the OPA644 is 0.008% differential gain and 0.009° differential phase to both NTSC and PAL standards.

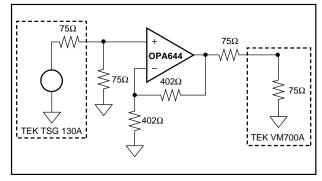


FIGURE 7. Configuration for Testing Differential Gain/Phase.

#### **NOISE FIGURE**

The OPA644's voltage and current noise spectral densities are specified in the Typical Performance Curves. For RF applications, however, Noise Figure (NF) is often the preferred noise specification since it allows system noise performance to be more easily calculated. The OPA644's Noise Figure vs Source Resistance is shown in Figure 8.



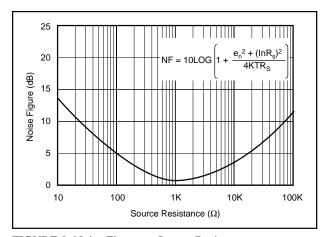


FIGURE 8. Noise Figure vs Source Resistance.

#### **SPICE MODELS**

Computer simulation using SPICE is often useful when analyzing the performance of analog circuits and systems. This is particularly true for Video and RF amplifier circuits where parasitic capacitance and inductance can have a major effect on circuit performance. SPICE models using MicroSim Corporation's PSpice are available for the OPA644. Contract Burr-Brown applications departments to receive a SPICE Diskette.

### **APPLICATIONS**

### **ENVIRONMENTAL (Q) SCREENING**

The inherent reliability of a semiconductor device is controlled by the design, materials and fabrication of the device—it cannot be improved by testing. However, the use of environmental screening can eliminate the majority of those units which would fail early in their lifetimes (infant mortality) through the application of carefully selected accelerated stress levels. Burr-Brown "Q-Screening" provides environmental screening to our standard industrial products, thus enhancing reliability. The screening illustrated in the following table is performed to selected stress levels similar to those of MIL-STD-883.

SCREEN	METHOD			
Internal Visual	Burr-Brown QC4118			
Stabilization Bake	Temperature = 150°C, 24 hrs			
Temperature Cycling	Temperature = -55°C to 125°C, 10 cycles			
Burn-In Test	Temperature = 125°C, 160 hrs minimum			
Centrifuge	20,000G			
Hermetic Seal	Fine: He leak rate < 5 X 10 <sup>-8</sup> atm cc/s, 30pPSiG Gross: per Fluorocarbon bubble test, 30pPSiG			
Electrical Tests	As described in specifications tables.			
External Visual	Burr-Brown QC5150			

NOTE: Q-Screening is available on HS package only.

#### **DEMONSTRATION BOARDS**

Demonstration boards to speed prototyping are available. Refer to the DEM-OPA64X datasheet for details.

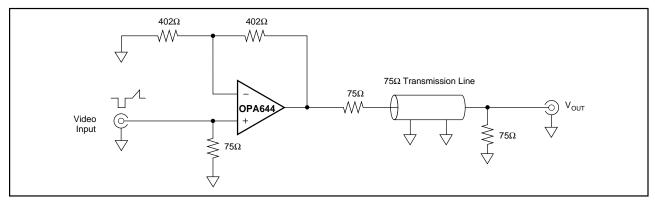


FIGURE 9. Low Distortion Video Amplifier.

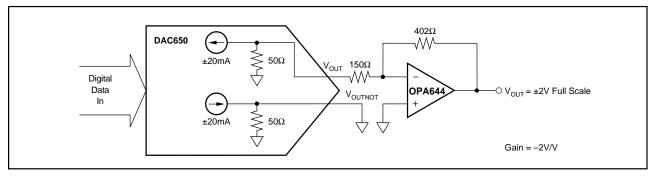


FIGURE 10. Output Amplification for the DAC650.



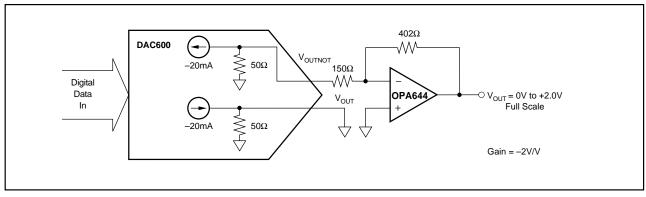


FIGURE 11. Output Amplification for the DAC600.

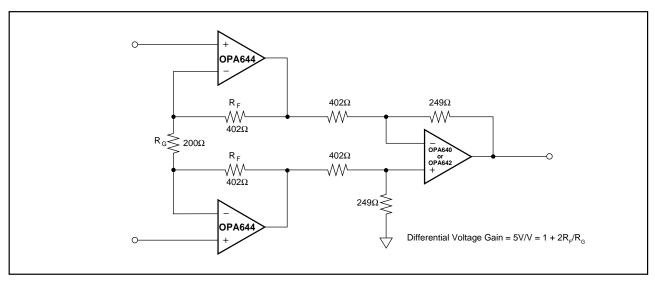


FIGURE 12. Wideband, Fast-Settling Instrumentation Amplifier.

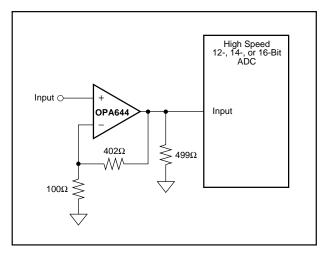
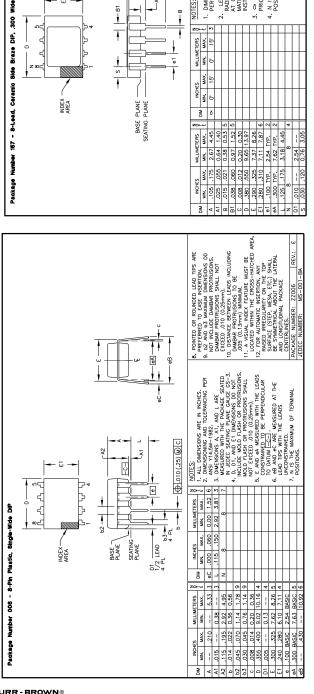


FIGURE 13. Low Distortion Gain Amplifier (G = +5V/V).



5. OUTLINES ON WHICH THE SEATING PLANES ON WHICH THE FEATING TO MONOGRAM WITH THE LEASE STAND TO SEATING THE SEATING THE LEAD ABOVE THE SEATING/BASE PLANE.

2. LEADS WITHIN ,005 IN. (0.13mm)
RADIUS OF TRUE POSITION (TP)
AT GAUGE PLANE WITH MAXIMUM
MATERIAL CONDITION AND UNIT
INSTALLED. DIMENSIONING AND TOLERANCING PER ANSI Y14.5-1973.

NOTES:

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INDEX AREA

BASE PLANE -SEATING PLANE -

APPLIES TO SPREAD LEADS PRIOR TO INSTALLATION.
 N IS THE NUMBER OF TERMINAL POSITIONS.

E1 DOES NOT INCLUDE PARTICLES OF PACKING MATERIALS.

8. A VISUAL INDEX FEATURE MUST BE LOCATED WITHIN THE CROSS-HATCHED AREA. 7. CONTROLLING DIMENSION: INCH.

